CHAPTER 18 : ACTUATORS

1.00.00 ELECTRICAL ACTUATORS WITH INTEGRAL STARTERS

1.01.00 SCOPE

This Specification covers the general requirements of Electric Motor Actuators for valves, dampers and gates.

All electric motor actuators shall be furnished in accordance with this general specification and the accompanying driven equipment specification.

1.02.00 CODES STANDARDS

All the equipment specified herein shall comply with the requirements of the latest issue of the relevant National & International standards.

The design and materials used for the components shall also comply with the relevant National & International standards.

As a minimum requirement, the following standards shall be complied with :

Electric motor operated actuators:IS 9334

Degrees of protection provided by enclosures at low:IS 2147

voltage switch gear and control gear

Flame Proof enclosure at electrical apparatus: IS 2148

Specification for three phase induction motors: IS 325

AC contactor for voltages not exceeding 1000 V:IS 2959

Degree of protection provided by enclosures for : IS 4691

Rotating electrical machinery

Specification for rotating electrical machines: IS 4722

For other code refer Section D28.

1.03.00 SERVICE CONDITIONS

The actuator shall be integral type and suitable for operation in a hot, humid and tropical atmosphere, highly polluted at places with coal dust & fly ash and shall be suitable for an ambient temperature ranging from (-) 20 deg C to (+) 70 deg C.

Actuators for explosion-hazardous applications shall in addition be certified Flameproof for Zones 1 and 2 (Divisions 1 and 2 Group gases).

2.00.00 RATING

(a) Supply Voltage & frequency: 415V +/- 10%, 3 Phase, 3 Wire 50HZ +/-5%.

(b) Sizing:-

For Open/Close at rated speed against designed differential pressure at 90% of rated voltage.

For isolating service:- three successive open-close operations or 15 mins, whichever is higher. For regulating service 150 starts per hour or required cycles, whichever is higher.

2.01.00 PERFORMANCES

2.01.01 The actuator shall meet the following performance requirements:

2.01.02 Open and close the valve completely and make leak-tight valve closure, without jamming.

2.01.03 Attain full speed operation before valve load is encountered and impart an unseating blow to start the valve in motion (hammer blow effect).

Operate the valve stem at standard stem speed and shall function against design differential pressure across the valve seat.

The motor reduction gearing shall be sufficient to lock the shaft when the motor is de-energised and prevent drift from torque switch spring pressure.

The entire mechanism shall withstand any shock resulting from closing with improper setting of limit switches or from lodging of foreign matter under the valve seat.

2.02.00 **SPECIFIC REQUIREMENT**

2.02.01 **CONSTRUCTION**

a) The actuator shall essentially comprise the drive motor, torque/ limit switches, gear train, clutch, hand wheel, position indicator and transmitter, . in built thermostat for overload protection,space heater and internal wiring.Actuator shall be integral type. Integral starters shall have facility to hook-up with plant DCS for positioning of limit and torque switches.

b) The actuator enclosure shall be totally enclosed, dust tight, weather proof (NEMA-6/IP-68) suitable for outdoor use without necessity of any canopy.

c) All electrical equipment, accessories and wiring shall be provided with tropical finish to prevent fungus growth.

d) The actuator shall be designed for mounting in any position without any lubricant leakage or operating difficulty.

e) A lockable local/remote selector switch shall also be provided for selecting mode of operation.

f) Gear Train :

Metal (Fibre gears are not acceptable) self-locking to prevent drift under torque switch (where ever applicable) spring pressure when motor is de-energised.

g) Manual Wheel:

Shall disengage automatically during motor operation.

2.02.02 **MOTOR**

The squirrel cage induction motor shall be designed for full voltage direct-on-line start, with starting current limited to 6 times full-load current. The motor shall be capable of starting at 85% of rated voltage and running at 80% of rated voltage at rated torque and also at 85% of rated voltage at 33% excess rated torque for a period of 5 minutes each. The motors shall otherwise generally confirm with technical specification for motors mentioned elsewhere in this specification.

The actuators shall be sized so as to open or close valves/ dampers at rated speed enclosure shall not be more than 70 degree 'C' over ambient temp. of 70 deg.C as these are subjected to higher ambient conditions due to their vicinity to operate fluid on continuous load operation. The actuators shall be suitable for a relative humidity of 95%. Class of insulation shall be class-F and type of enclosure shall be IP-68.

The actuators shall be designed to be self locking upon loss of power. Motor shall be designed to close in 30 secs from full open position and shall have adequate capacity to open and close under full unbalanced design pressure.

The actuators shall be flange mounted to valve bonnets or with gearing and disengaging hand wheel for dampers.

2.02.03 **LIMIT SWITCHES**

Each motor actuator shall have Six (6) rotary drum position limit switches with two for open each with 2 NO + 2NC contacts and two for close each with 2 NO + 2 NC contacts positions, each with adjustable setting between fully open and fully closed positions. Each rotary drum limit switch shall have two (2) limit switches for intermediate open position each with 2 NO + 2 NC contacts. The limit switches shall have capacity of 5A at 240V AC or 0.5A at 220V DC.

Each motor actuator shall also have two (2) torque limit switches with four (4) normally opened and four (4) normally closed contacts each.

The torque switches shall have a minimum accuracy of 3% of set value. The torque switches shall be provided with calibrated knobs for setting desired torque and separate knobs shall be provided for open and close torque switches. The torque and position limit switches shall be housed in a separate enclosure with protection class as that of actuator.

The motor operators/actuators shall conform to AWWA specification and shall be capable of meeting 150 percent of unseating torque at specified voltage.

The motor actuators shall have 2 nos. potentiometric type transmitters of 100 ohm rating.

Torque switches shall function to stop the motor on closing. Upon actuation by the torque clutch it is restricted its attempt to open or close, thereby causing an overloading torque. Torque switches shall be non-self resetting type only (i.e.) once a particular direction torque switch operates, it will get resetted only when the equipment is operated in other direction.

All six (6) limit switches shall be changeover type and adjustable besides having the snap facility. All limit switches, contacts shall be wired up independently upto the terminal block.

2.02.04. **POSITION INDICATOR/TRANSMITTER**

a) Motor actuators shall be provided with clearly visible local position indicators mounted on the operator assembly itself. Suitable transducers shall be provided for remote indication of the position.

b) To be provided for 0 to 100% travel.

c) As required. Suitable for stabilized 4-20 mA signal, 2 wire inductive type, 24 volts DC operated.

2.02.05. **HAND WHEEL**

Hand wheel shall enable manual operation in case of power failure but it shall get automatically disengaged when once the motor starts functioning. The effort required to operate manually shall not exceed 18 Kg.

2.02.06 **SPACE HEATER**

Provision of space heater, if necessary, shall also be made with servomotor limit switch compartments. The space heaters shall be suitable for operation at 240V AC and its rating shall be indicated by the tenderer. Space heater circuit shall be complete with thermostat.

2.02.07 **TERMINAL BOX**

a) The terminals, terminal boards, terminal boxes, winding coils and associated equipments shall be suitable for connection to supply system having short circuit capacity specified in data sheet and clearance time determined by associated fuses. The terminal boxes shall be totally enclosed.

b) 650V grade for power cables.

2.02.08 **WIRING**

All wiring connections for various limit and torque switches, space heaters, position transmitters shall be brought out on separate terminal boards mounted on the valve, having liberal space for wiring and making connections to Purchaser's external circuits. Plug in type terminals shall be used suitable for analog/digital application. There shall be atleast 5 terminal spare to terminate spare cores of cable. Size of each control terminal shall be such that two (2) nos. lugged 2.5 sq.mm cable can be terminated on

each side. Power terminals shall be suitable for termination of 6 sq.mm lugged wire or as required depending on the motor capacity.

Motor terminal box and actuator terminal box shall be provided with cable glands to suit cable type and size.

Adequate earthing terminals preferably not less than 8 SWG GI wire shall be provided for suitable earthing system. Two earthing terminals shall be provided per motor, one No. on either side of the motor. The actuator shall include a diagnostic module, which will store and enable down load historical down load operation and torque data to permit analysis of actuator and valve in service performance. Data down load shall be carried out without removing any covers and all shall be available locally to the actuator or remotely via telecommunication data transfer. Diagnostic and configuration software shall be made for user PC system.

2.02.09 INTERFACES:

Open/Close command termination logic with position & torque Limit Switches, positioner circuit shall be suitably built in the PCB inside the actuator.

(a) For Binary Drive (both ON-OFF and INCHING type) :- Open/Close command & status thereof and disturbance monitoring signal (common contact for Overload, Thermostat, control supply failure, L/R selector switch at local & other protections operated) shall be provided.

Interface with the control system shall be through hardware signal only. Inter posing relays provided (with coil burden 2.5 VA) in the actuator shall be energized to initiate opening and closing, by 24V DC signal from the external control system.

(b) For Modulating Drive:- the command to actuator shall be in form of 4-20mA signal. The necessary positioning circuit and motor protection shall be provided

(c) Open/close command termination logic shall be suitably built inside actuator.

2.02.10 **DRAWING AND DATA AND MANUALS**

Data sheet for each of the actuator shall be furnished alongwith internal wiring diagram, suggested control schematic and limit switch contact development and manufacturer's catalogues.

2.02.11 **NAME PLATE**

Name plate shall be provided on the actuators with at least following data (a) Tag no. (b) Torque Rating (c) Full travel time.

2.02.12 **PAINTING**

The actuator shall be painted with epoxy based paint (the colour shall be indicated by the supplier). Paint shade shall be RAL 7032.

2.02.13 **PACKING**

The actuators shall be properly packed for transport by rail/ road/sea as applicable.

2.02.14 **OVERLOAD PROTECTION**

The actuator motor shall be provided with integral starter along with thermistor for overload protection.

2.02.15 **TESTS**

The actuator and all components thereof shall be subject to routine factory tests as per relevant IS Standards. In addition, if any special test is called for in equipment specification, the same shall be performed.

Following routine test shall be conducted as per IEC/IC standard. (a) Meggar Test, (b) Continuity test, (c) Operational test. Test certificates duly signed by inspecting agency shall be furnished.

The actuator shall be type tested as per IEC/National Standard, by international/national recognised test house. The test certificates issued by this house shall be furnished.

2.02.16 **TEST WITNESS**

Tests shall be performed in the presence of Owner/Purchaser's representative so desired by the Owner/ Purchaser. The contractor shall give at least fifteen (15) days advance notice of the date when the tests are to be carried out.